

# Performance Evaluation of Parallel Gram-Schmidt Re-Orthogonalization Methods

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**Abstract.** In this paper, the performance of the five kinds of parallel re-orthogonalization methods by using the Gram-Schmidt (G-S) method is reported. Parallelism of the re-orthogonalization process depends on the implementation of G-S orthogonalization process, i.e. Classical G-S (CG-S) and Modified G-S (MG-S). To relax the parallelism problem, we propose a new hybrid method by using both of the CG-S and MG-S. The HITACHI SR8000 of 128 PEs, which is a distributed memory super-computer, is used in this performance evaluation.

## 1 Introduction

The orthogonalization process is one of the most important processes to perform several linear algebra computations, such as eigendecomposition and QR decomposition [3, 10, 11]. Many researchers have been attention for QR decomposition [2, 5, 6, 12, 13] notwithstanding, we focus on the re-orthogonalization process in this paper. This is because, a lot of iterative methods for solving linear equations and eigenvector computations needs the re-orthogonalization process to keep the accuracy of solution. For instance, the GMRES method, which is one of the latest iterative algorithms, requires the re-orthogonalization to obtain base-vectors according to the number of its re-start frequency [4]. The approach of parallel re-orthogonalization is the main difference with respect to conventional parallel approaches based on QR decomposition [6, 12, 13].

Recently, there are a number of parallel machines, because parallel processing technologies have been established. In this reason, many researchers try to parallelize the orthogonalization process. It is known that, however, the parallelism of the process depends on the number of orthogonalized vectors we needed [7, 8]. The orthogonalized process, therefore, is classified as the following two kinds of processes in this paper:

- QR decomposition

The orthogonalization process to obtain the normalized and orthogonalized vectors  $q_1, q_2, \dots, q_n$  by using the normalized vectors  $a_1, a_2, \dots, a_n$ .

– Re-orthogonalization

The orthogonalization process to obtain the normalized and orthogonalized vector  $q_i$  by using the normalized and orthogonalized vectors  $q_1, q_2, \dots, q_{i-1}$ .

This paper discusses how to parallelize the re-orthogonalization process by using the Gram-Schmidt (G-S) orthogonalization method. The focus is especially the parallelization of Classical G-S (CG-S) method, since the CG-S method has high parallelism. The CG-S method, however, has a trade-off problem between accuracy and execution speed. For example, T.Katagiri reported that more 90% execution time is wasted by using MG-S method in a parallel eigensolver [8]. From this back ground, main aim of this paper is a proposition of new parallel G-S algorithm to relax the trade-off problem.

This paper is organized as follows. Chapter 2 is the explanation of sequential G-S algorithms in the viewpoint of data dependency. Chapter 3 describes parallel G-S algorithms based on the sequential G-S algorithms. Chapter 4 proposes the new algorithm. Chapter 5 is the evaluation of the new algorithm by using the HITACHI's parallel super-computer. Finally, Chapter 6 summarizes the findings of this paper.

## 2 Sequential algorithms of G-S re-orthogonalization method

It is widely known that there are following two methods to perform re-orthogonalization by using the G-S method. They are called as Classical G-S (CG-S) method and Modified G-S (MG-S) method. The CG-S method is a simply implemented method in the formula of the G-S orthogonalization, and the MG-S method is a modified one in order to obtain high accuracy. In this chapter, we will explain the difference of them in the viewpoint of data dependency.

### 2.1 Classical Gram-Schmidt (CG-S) Method

The CG-S method to perform the re-orthogonalization is shown in Figure 1. The notation of  $(\cdot, \cdot)$  in Figure 1 means an inner product.

<pre> (1)  <math>q_i = a_i</math> (2)  <b>do</b> <math>j = 1, i - 1</math> (3)  <math>q_i = q_i - (q_j^T, a_i)q_j</math> (4)  <b>enddo</b> (5)  Normalization of <math>q_i</math>. </pre>
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**Fig. 1.** The CG-S method in re-orthogonalization to the vector  $q_i$ .

Figure 1 shows that the most inner kernel (3) has a parallelism. The nature of this can be explained as the parallelism of the inner product  $(q_j^T, a_i)$ , since the

inner product can be performed parallelly for  $j$ -loop when we obtain the initial vector of  $a_i$ .

## 2.2 Modified Gram-Schmidt (MG-S) Method

The MG-S method in re-orthogonalization is shown in Figure 2.

$  \begin{aligned}  \langle 1 \rangle & a_i^{(0)} = a_i \\  \langle 2 \rangle & \mathbf{do} \ j = 1, i - 1 \\  \langle 3 \rangle & a_i^{(j)} = a_i^{(j-1)} - (q_j^T, a_i^{(j-1)})q_j \\  \langle 4 \rangle & \mathbf{enddo} \\  \langle 5 \rangle & \text{Normalization of } q_i = a_i^{(i-1)}.  \end{aligned}  $
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**Fig. 2.** The MG-S method in re-orthogonalization to the vector  $q_i$ .

Figure 2 shows that there is no parallelism to the inner product of  $\langle 3 \rangle$ , since the inner product depends on the defined vector  $a_i^{(j-1)}$  for  $j$ -loop. This is the basic difference to the CG-S method. From this reason, many researchers believe that the re-orthogonalization by the MG-S method is an unsuitable method for parallel processing.

## 3 Parallelization of G-S orthogonalization method

In the view point of parallel processing, the re-orthogonalization by the G-S method has different behavior according to the data distribution method for the orthogonalized vectors  $q_1, q_2, \dots, q_{i-1}$  [8]. We will explain this in the chapter.

### 3.1 A case of column-wise distribution

First of all, we explain a simple distribution method, named column-wise distribution (CWD). The CWD is a distribution that the whole elements of the normalized vectors  $a_i$  and the normalized and orthogonalized vectors  $q_1, q_2, \dots, q_{i-1}$  are distributed to each PE (Processing Element).

Next is a discussion that how to implement parallel algorithms based on the CWD.

**A case of CG-S method** Figure 3 shows a re-orthogonalization algorithm in CWD. The notation of “Local” in Figure 3 shows that following formula should be performed by using local data (distributed data) only.

According to Figure 3, there is a parallelism for computing the kernel of  $\langle 9 \rangle$ .

```

(1)  $q_i = a_i$ 
(2) if (I have  $a_i$ ) then
(3)   Broadcast ( $a_i$ )
(4) else
(5)   receive ( $a_i$ )
(6)    $q_i = 0$ 
(7) endif
(8) do  $j = 1, i - 1$ 
(9)   Local  $q_i = q_i - (q_j^T, a_i) q_j$  enddo
(10) if (I have  $a_i$ ) then
(11)   do  $j = 1, i - 1$ 
(12)     receive ( $q_j$ ) from PE that holds  $q_j$ 
(13)     Local  $q_i = q_i + q_j$  enddo
(14) else
(15)   send ( $q_i$ )
(16) endif
(17) Normalization of  $q_i$ .

```

**Fig. 3.** The CG-S method in column-wise distribution.

```

(1)  $a_i^{(0)} = a_i$ 
(2) do  $j = 1, i - 1$ 
(3)   receive ( $a_i^{(j-1)}$ ) from PE that holds  $a_i^{(j-1)}$ 
(4)   Local  $a_i^{(j)} = a_i^{(j-1)} - (q_j^T, a_i^{(j-1)}) q_j$ 
(5)   send ( $a_i^{(j)}$ ) to PE that holds  $a_i^{(j+1)}$ 
(6) enddo
(7) Normalization of  $q_i = a_i^{(i-1)}$ .

```

**Fig. 4.** The MG-S method in column-wise distribution.

**A case of MG-S method** Figure 4 shows a re-orthogonalization algorithm in CWD.

Please note that there is no parallelism for computing the kernel of (4) according to Figure 3, because PE holds  $a_i^{(j-1)}$  and PE holds  $a_i^{(j)}$  are located on different place in CWD.

From this reason, the re-orthogonalization by MG-S method in CWD has basically poor parallelism.

### 3.2 A case of row-wise distribution

Next we will explain another well-known distribution, named row-wise distribution (RWD). The RWD is a distribution that the elements of vectors ( $a_i, q_i$ ) and orthogonalized vectors  $q_1, q_2, \dots, q_{i-1}$  are distributed to different PEs. Please note



⟨1⟩	$a_i^{(0)} = a_i$
⟨2⟩	<b>do</b> $j = 1, i - 1$
⟨3⟩	Local $(q_j^T, a_i^{(j-1)})$
⟨4⟩	Global sum of $\eta = (q_j^T, a_i^{(j-1)})$ .
⟨5⟩	Local $a_i^{(j)} = a_i^{(j-1)} - \eta q_j$
⟨6⟩	<b>enddo</b>
⟨7⟩	Normalization of $q_i = a_i^{(i-1)}$ .

**Fig. 6.** The MG-S method in row-wise distribution.

**Comparison of the number of communications** Now we compare the number of execution times for the Global sum operation in the MG-S and CG-S methods. Let the number of re-orthogonalization  $i$  be fixed as  $k$ . It is clear that the MG-S method requires  $(k^2 - k)/2$  times of the Global sum operation while the CG-S method requires  $k - 1$  times. Thus, from view point of execution times, the CG-S method is superior to the MG-S method. The CG-S method, however, has lower accuracy than the accuracy of the MG-S method. Therefore, we can not determine the best parallel method in the RWD.

From the viewpoint of these variations, the RWD will be a good choice. The discussion on the RWD, however, is omitted in this paper. The reason is that the distributing the elements of vectors makes the implementation difficult in many iterative algorithms and poor utility for many users.

## 4 Proposal of the Hybrid Gram-Schmidt (HG-S) method

In this chapter, we propose a new parallel re-orthogonalization method, named Hybrid Gram-Schmidt (HG-S) method.

### 4.1 Basic idea

We have explained that there is a trade-off problem between accuracy and parallel execution speed in G-S method. The following is a summary of the problem.

- **CG-S Method** Accuracy: Low, Parallelism: Yes
- **MG-S Method** Accuracy: High, Parallelism: None

To relax the problem, using both of CG-S and MG-S methods for re-orthogonalization is one of reasonable ways. We call this “Hybrid”-ed G-S method as HG-S method in this paper.

### 4.2 The HG-S re-orthogonalization method

Figure 7 shows a sketch of the algorithm for the HG-S method. Please note that the code of Figure 7 shows the nature of re-orthogonalization process, since many iterative algorithms, for example the inverse iteration method for eigenvector computation, needs the re-orthogonalization like Figure 7.

```

do  $i = 1, \dots, max\_num\_vectors$ 
....
  do  $iter = 1, \dots, max\_iter$ 
    ....
    Re-orthogonalization ( $q_i$ ) by using the CG-S Method.
    ....
    if ( $q_i$  is converged) break the  $iter$ -loop.
  enddo
  Re-orthogonalization ( $q_i$ ) by using the MG-S Method.
....
enddo

```

**Fig. 7.** The HG-S method in re-orthogonalization.

## 5 Experimental Results

The HG-S method by using a distributed memory parallel machine is evaluated in this chapter. To evaluate the HG-S method, we implemented the HG-S method to Inverse Iteration Method (IIM) for computation of eigenvectors.

### 5.1 Experimental environment

The HITACHI SR8000/MPP is used in this experiment. The HITACHI SR8000 system is a distributed memory, message-passing parallel machine of the MIMD class. It is composed of 144 nodes, each having 8 Instruction Processors (IPs), 14.4GFLOPS of theoretical peak performance, 16 Gigabytes of main memory, interconnected via a communication network with the topology of a three-dimensional hyper-crossbar. The peak interprocessor communications bandwidth is 1.6 Gbytes/s in each direction.

The SR8000 system has two types of parallel environments. One is intra-node parallel processing, and the other is inter-node parallel processing. The intra-node parallel processing is so-called parallel processing as a sheard memory parallel machine, and it never performs interprocessor communications. On the other hand, the inter-node parallel processing is similar to parallel processing as a distributed memory parallel machine, and it must perform interprocessor communications. The HITACHI Optimized Fortran90 V01-04 compiler is used. In this experiment, `-opt=ss -parallel=0` is used as a compile option in the inter-node parallel processing.

As communication library, optimized MPI (Message Passing Interface) by HITACHI is used in this experiment.

### 5.2 Details of implemented re-orthogonalization methods

We implemented parallel re-orthogonalization methods in IIM for eigenvector computation [10]. The details of the IIM algorithm are summarized as follows.

- Object Matrix : Tridiagonal real symmetric matrix  $T$
- Method : The Rayleigh quotient IIM
- Max Iterative Numbers : 40
- Requirement residual :  $\|T\|_1 \times \epsilon$  (Machine Epsilon)

We have developed an efficient parallel eigensolver by using a reduced communication method [9]. The IIM method is also available for the eigensolver, therefore, we measure the execution time for the routine of IIM.

The test matrices are chosen as the following.

- Matrix(1) : Tridiagonal matrix reduced from the Frank matrix
  - Dimension : 10,000
  - The length to decide the clustered eigenvalues : 58471.532
  - The number of groups for the clustered eigenvalues : 8
  - The maximum number of clustered eigenvalues : 9,993
- Matrix(2) : Glued Wilkinson  $W_{21}^+$  Matrix,  $\delta = 1.0$ 
  - Dimension : 10,000
  - The length to decide the clustered eigenvalues : 64.998
  - The number of groups for the clustered eigenvalues : 1
  - The maximum number of clustered eigenvalues : 10,000
- Matrix(3) : Glued Wilkinson  $W_{21}^+$  Matrix,  $\delta = 10^{-14}$ 
  - Dimension : 10,000
  - The length to decide the clustered eigenvalues : 0.129
  - The number of groups for the clustered eigenvalues : 13
  - The maximum number of clustered eigenvalues : 2

Please note that the re-orthogonalization is performed to keep accuracy of eigenvectors. The number of re-orthogonalized eigenvectors is same as the number of clustered eigenvalues.

Next, we summarize the implemented parallel re-orthogonalization methods as follows.

- CG-S (1) : Local Orthogonalization MG-S
- CG-S (2) : Local Orthogonalization CG-S
- MG-S
- HG-S
- IRCG-S : Iterative Refinement CG-S Method [1, 10]
- NoOrt : Not Re-orthogonalized

There are two kinds of methods in the parallel re-orthogonalization of CG-S method. The CG-S(1) is a method that CG-S is performed inter PEs and MG-S is performed to intra PE data. The CG-S(2) is a method that CG-S is performed inter PEs, and CG-S is also performed to intra PE data.

The IRCG-S method shown the above is called Iterative Refinement CG-S Method, and this method performs CG-S method multi-times. In this experiment, the number of CG-S method is fixed as 2 times.

### 5.3 The results of experiment

Table 1 shows the execution time for the five parallel re-orthogonalization methods in IIM. From the restriction of super-computer environment, over  $\lfloor 64/\lceil p/8 \rceil \rfloor$  hours jobs are automatically killed, where  $p$  is the number of PEs.

Table 2 shows the orthogonalization accuracy of the calculated eigenvectors by IIM, which are measured by the Frobenius norm. The Frobenius norm of  $n \times n$  matrix  $A = (a_{ij})$ ,  $i, j = 1, \dots, n$  is defined as:

$$\|A\|_F \equiv \sum_{i=1}^n \sqrt{a_{ij}^2}. \quad (1)$$

**Table 1.** The execution time of each method in the IIM. The unit is in seconds.

(a) Test Matrix(1): Reduced Frank Matrix

#PEs(IPs)	CG-S(1)	CG-S(2)	MG-S	HG-S	IRCG-S	NoOrt
8	6604	6527	38854	6604	12883	23.857
16	3646	3526	24398	3574	6987	12.065
32	2061	2059	28050	2082	3906	7.044
64	1633	1559	27960	1614	3059	3.025
128	2091	2204	>14400	2027	3978	1.808

(b) Test Matrix(2): Glued Wilkinson Matrix  $\delta = 1.0$

#PEs(IPs)	CG-S(1)	CG-S(2)	MG-S	HG-S	IRCG-S	NoOrt
8	7779	7898	77851	10825	14673	30.88
16	4358	4264	61242	4348	7595	15.31
32	2533	2347	32131	2480	4429	8.99
64	2152	2110	>28800	2189	3241	4.44
128	2696	2390	>14400	2450	4699	2.45

(c) Test Matrix(3): Glued Wilkinson Matrix  $\delta = 10^{-14}$

#PEs(IPs)	CG-S(1)	CG-S(2)	MG-S	HG-S	IRCG-S	NoOrt
8	0.558	0.561	0.510	0.593	2.494	0.59
16	0.554	0.696	1.922	1.697	0.619	0.33
32	0.364	0.828	0.970	0.293	0.858	0.20
64	0.530	0.451	0.521	0.431	0.378	0.38
128	0.277	0.221	0.315	0.269	0.259	0.07

### 5.4 Discussion

**Test matrix (1)** Table 1 (a) shows there was poor parallelizm for MG-S. The reason is explained as no parallelizm in MG-S process in CWD. On the

**Table 2.** The eigenvector accuracy of each method in the IIM. The norm of Frobenius is used.

(a) Test Matrix(1): Reduced Frank matrix  
(MG-S:Residual of  $\max_i \|Ax_i - \lambda x_i\|_2 = 0.1616\text{E-}006$ )

#PEs(IPs)	CG-S(1)	CG-S(2)	MG-S	HG-S	IRCG-S	NoOrt
8	0.6485E-012	0.6505E-012	0.6670E-012	0.6485E-012	0.6455E-012	1.414
16	0.6621E-012	0.6627E-012	0.6666E-012	0.6620E-012	0.6613E-012	1.414
32	0.6892E-012	0.6895E-012	0.6664E-012	0.6893E-012	0.6899E-012	1.414
64	0.9422E-012	0.9413E-012	0.6665E-012	0.9412E-012	0.9419E-012	1.414
128	0.1546E-011	0.1547E-011	Time Out	0.1540E-011	0.1549E-011	1.414

(b) Test Matrix(2): Glued Wilkinson Matrix  $\delta = 1.0$   
(MG-S:Residual of  $\max_i \|Ax_i - \lambda x_i\|_2 = 0.4476\text{E-}007$ )

#PEs(IPs)	CG-S(1)	CG-S(2)	MG-S	HG-S	IRCG-S	NoOrt
8	0.1261E-011	0.2679E-011	0.1432E-011	0.3087E-008	0.2137E-012	283.7
16	0.1255E-011	0.6093E-011	0.1971E-011	0.1349E-011	0.4658E-012	282.3
32	2.0191	1.4260	0.5255E-012	1.967	1.9455	283.4
64	3.7387	3.5735	Time Out	3.492	3.7619	284.9
128	5.2028	4.7178	Time Out	4.9206	5.0163	284.9

(c) Test Matrix(3): Glued Wilkinson Matrix  $\delta = 10^{-14}$   
(MG-S:Residual of  $\max_i \|Ax_i - \lambda x_i\|_2 = 0.1625\text{E-}010$ )

#PEs(IPs)	CG-S(1)	CG-S(2)	MG-S	HG-S	IRCG-S	NoOrt
8	0.3966E-007	31.50	0.3966E-007	0.3966E-007	0.3966E-007	31.50
16	0.3966E-007	31.50	0.3966E-007	0.3966E-007	0.3966E-007	31.50
32	0.3967E-007	31.38	0.3966E-007	0.3967E-007	0.3967E-007	31.50
64	0.3966E-007	31.31	0.3966E-007	0.3966E-007	0.3966E-007	31.50
128	0.3967E-007	31.06	0.3966E-007	0.3967E-007	0.3967E-007	31.50

other hand, by using CG-S Method, we obtained speed-up factors increasing the number of PEs.

For HG-S method, the HG-S was faster than CG-S. This is a surprising result in a sense, because HG-S performs multi-times CG-S and one-time MG-S. We think the main reason is that by using the HG-S method, total number of iterations in IIM is reduced by using better accuracy eigenvalues with comparison to eigenvectors orthogonalized by CG-S only.

In the case of the Frank matrix, we could not find the difference of accuracy for eigenvectors except for not-orthogonalized case. From this reason, HG-S is the best method in this case.

**Test matrix (2)** First of all, we have to mention that the accuracy of eigenvectors was very poor when we use over 32 PEs except for MG-S method. From this reason, we should select the MG-S method in this case. As a result, if we use 16 PEs and 8 PEs, the methods of CG-S(1), CG-S(2) and HG-S will be a considerable method in this case.

From the execution time, we also had a surprising result for MG-S, because although the MG-S method has no parallelism in this case, there are speed-up factors of MG-S. We think that the result is caused by reducing data amount by parallel processing, however, detail analysis for this result is a future work.

**Test matrix (3)** In this case, the execution time of each method is quite small compared to the cases of the matrix (1) and (2). This reason is explained as the implementation of parallel IIM routine. In our IIM routine, if an element of sub-diagonals of the tridiagonal matrix  $T$  is quite small value such as machine  $\epsilon$ , the diagonal matrices separated by the element are treated as independent matrices of the eigensystem. This separation can reduce computational complexity and increase parallelism. In the case of matrix (3), the test matrix is separated by several small diagonal matrices, each has a dimension of 21. From this reason, the number of re-orthogonalizations is reduced, as a result of the nature, the execution time is also very shorten.

For the results of the accuracy, we could find that the accuracy of CG-S(2) method was poor in this matrix with comparison to the case of CG-S(1) method. From this result, therefore, we can say that data which holds intra PE should be re-orthogonalized by using MG-S method, even CG-S method is used for inter PEs.

## 6 Conclusion

In this paper, we have proposed a hybrid Gram-Schmidt re-orthogonalized method, and evaluated the five kinds of parallel re-orthogonalization methods including the new hybrid method by using IIM for eigenvector computation.

From the experimental result, the new hybrid method also has an accuracy problem for computed eigenvectors, but it has a benefit for parallel execution

time compared to CG-S method. The main reason of this is using higher accuracy eigenvectors than that of CG-S orthogonalized, however, detail analysis is needed.

The analysis and additional experiments for the test matrices are important future work.

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